

Basics of AI and Machine Learning

Other Planning Formalisms

David Speck

Linköping University

Automated Planning: Overview

Chapter overview: automated planning

- Introduction
- The STRIPS Planning Formalism
- **Other Planning Formalisms**
- Planning Heuristics
- Alternatives to Heuristic Search

Four Formalisms

Reminder: Four Planning Formalisms

- A description language for state spaces (**planning tasks**) is called a **planning formalism**.
- We introduce four planning formalisms:
 - ① STRIPS (Stanford Research Institute Problem Solver)
 - ② ADL (Action Description Language)
 - ③ SAS⁺ (Simplified Action Structures)
 - ④ PDDL (Planning Domain Definition Language)

ADL, SAS⁺ and PDDL

Basic Concepts of ADL

basic concepts of ADL:

- Like STRIPS, ADL uses propositional variables (true/false) as state variables.
- preconditions of actions and goal are **arbitrary logic formulas** (action applicable/goal reached in states that satisfy the formula)
- in addition to STRIPS effects, there are **conditional effects**: variable v is only set to true/false if a given logical formula is true in the current state

Basic Concepts of SAS⁺

basic concepts of SAS⁺:

- very similar to STRIPS: state variables not necessarily binary, but with given **finite domain** (cf. CSPs)
- states are **assignments** to these variables (cf. CSPs)

Basic Concepts of SAS⁺

basic concepts of SAS⁺:

- very similar to STRIPS: state variables not necessarily binary, but with given **finite domain** (cf. CSPs)
- states are **assignments** to these variables (cf. CSPs)
- preconditions and goals given as **partial assignments**
example: $\{v_1 \mapsto a, v_3 \mapsto b\}$ as preconditions (or goals)
 - If $s(v_1) = a$ and $s(v_3) = b$,
then the action is applicable in s (or goal is reached)
 - values of other variables do not matter

Basic Concepts of SAS⁺

basic concepts of SAS⁺:

- very similar to STRIPS: state variables not necessarily binary, but with given **finite domain** (cf. CSPs)
- states are **assignments** to these variables (cf. CSPs)
- preconditions and goals given as **partial assignments**
example: $\{v_1 \mapsto a, v_3 \mapsto b\}$ as preconditions (or goals)
 - If $s(v_1) = a$ and $s(v_3) = b$,
then the action is applicable in s (or goal is reached)
 - values of other variables do not matter
- effects are **assignments to subset** of variables
example: effect $\{v_1 \mapsto b, v_2 \mapsto c\}$ means
 - In the successor state s' , $s'(v_1) = b$ and $s'(v_2) = c$.
 - All other variables retain their values.

Basic Concept of PDDL

- PDDL is the standard language used in practice to describe planning tasks.
- descriptions in (restricted) predicate logic instead of propositional logic (\rightsquigarrow even more compact)
- other features like **numeric variables** and **derived variables (axioms)** for defining “macros”
(formulas that are automatically evaluated in every state and can, e.g., be used in preconditions)
- There exist defined PDDL fragments for STRIPS and ADL; many planners only support the STRIPS fragment.

Examples: see <http://editor.planning.domains/>

Summary

Summary

planning formalisms:

- **STRIPS**: particularly simple, easy to handle for algorithms
 - binary state variables
 - preconditions, add and delete effects, goals: sets of variables
- **ADL**: extension of STRIPS
 - **logic formulas** for complex preconditions and goals
 - **conditional effects**
- **SAS⁺**: extension of STRIPS
 - state variables with **arbitrary finite domains**
- **PDDL**: input language used in practice
 - based on predicate logic
(more compact than propositional logic)
 - only partly supported by most algorithms
(e.g., STRIPS or ADL fragment)